

Technical data Actuator controls

General information

AM 01.1/ AM 02.1 actuator controls for controlling multi-turn actuators of the SA/SAR .1, SA/SAR .2 type ranges and part-turn actuators of the SQ/SQR .2 type range.

Features and functions

Power supply	Standard voltages AC: Refer to table: 3-phase AC standard voltages [► 2] Refer to table: 1-phase AC standard voltages [► 2] Special voltages AC: Refer to table: 3-phase AC special voltages [► 2] Refer to table: 1-phase AC special voltages [► 2] Permissible variation of mains voltage: $\pm 10\%$ Permissible variation of mains frequency: $\pm 5\%$ Further permissible variations of the mains voltage (options): $-20\%/+15\%$, $-20\%/+10\%$, $-30\%/+30\%$, $-30\%/+10\%$	
External supply of the electronics (option)	24 V DC: $+20\%/-15\%$ Current consumption: Basic version approx. 250 mA, with options up to 500 mA For external electronics supply, the power supply of actuator controls must have an enhanced isolation against mains voltage in compliance with IEC 61010-1 and the output power be limited to 150 VA.	
Current consumption	Current consumption of controls depending on mains voltage: For permissible variation of mains voltage of $\pm 10\%$: 100 to 120 V AC = max. 575 mA 208 to 240 V AC = max. 275 mA 380 to 690 V AC = max. 160 mA Current consumption for mains voltage variation: $> \pm 10\%$ on request	
Overvoltage category	Category III according to IEC 60364-4-44	
Rated power	Actuator controls are designed for nominal motor power, refer to Electrical data pertaining to the actuator.	
Switchgear	Standard:	Reversing contactors (mechanically and electrically interlocked) for AUMA power classes A1/A2
	Options:	Reversing contactors (mechanically and electrically interlocked) for AUMA power classes A1/A2 with additional contacts, 1 NC + 1 NO each
		Reversing contactors (mechanically and electrically interlocked) for AUMA power class A3
		Thyristor unit for mains voltage up to 600 V AC (recommended for modulating actuators) for AUMA power classes B1, B2 and B3
	Reversing contactors are designed for a lifetime of 2 million starts. For applications requiring a high number of starts, we recommend using thyristor units. For the assignment of AUMA power classes, please refer to Electrical data pertaining to the actuator	
Control inputs	3 digital inputs: OPEN, STOP, CLOSE (via opto-isolator with one common), respect minimum pulse duration for modulating actuators	
Control voltage/current consumption for control inputs	Standard:	24 V DC, current consumption: approx. 10 mA per input
	Option:	115 V DC, current consumption: approx. 15 mA per input
Status signals (output signals)	Standard:	5 output contacts: 4 NO contacts with one common, max. 250 V AC, 0.5 A (resistive load) - Default configuration: End position CLOSED, end position OPEN, selector switch REMOTE, selector switch LOCAL 1 potential-free change-over contact, 250 V AC, 5 A (resistive load) for collective fault signal - Default configuration: Torque fault, phase failure, motor protection tripped
	Options:	5 output contacts with integrated running indication (blinking) for directions OPEN and CLOSE in combination with blinker transmitter 4 NO contacts with one common, max. 250 V AC, 0.5 A (resistive load) - Default configuration: End position and running indication CLOSED, end position OPEN, selector switch REMOTE, selector switch LOCAL 1 potential-free change-over contact, 250 V AC, 0.5 A (resistive load) for collective fault signal - Default configuration: Torque fault, phase failure, motor protection tripped
Voltage output	Standard:	Auxiliary voltage 24 V DC: max. 100 mA for supply of control inputs, galvanically isolated from internal voltage supply
	Option:	Auxiliary voltage 115 V AC: max. 30 mA for supply of control inputs, galvanically isolated from internal voltage supply (Not possible in combination with PTC tripping device)

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Local controls	Standard:	- Selector switch LOCAL - OFF - REMOTE (lockable in all three positions) - Push buttons OPEN, HALT, CLOSE 6 indication lights: End position CLOSED (yellow), collective fault signal (red), end position OPEN (green)
	Options:	- Protection cover, lockable - Special colours for the 3 indication lights
Application functions		- Selectable type of seating, limit or torque seating for end position OPEN and end position CLOSED - Overload protection against excessive torques across the whole travel - Excessive torque (torque fault) can be excluded from collective fault signal. - Phase failure monitoring with automatic phase correction - Push-to-run operation or self-retaining in REMOTE - Push-to-run operation or self-retaining in LOCAL - Blinker signal from actuator (option) for running indication via indication lights of local controls can be activated/deactivated
Motor protection evaluation	Standard:	Monitoring the motor temperature in combination with thermoswitches within actuator motor
	Options:	- Additional thermal overload relay in actuator controls combined with thermoswitches within actuator - PTC tripping device in combination with PTC thermistors within actuator motor
Electrical connection	Standard:	AUMA plug/socket connector with screw-type connection
	Option:	- Terminals or crimp-type connection - Gold-plated control contacts (pins and sockets)
Threads for cable entries	Standard:	Metric threads
	Option:	NPT threads, G threads
Wiring diagram (basic version)	MSP1110KC3--F18E1 TPA00R1AA-101-000	

Table 1: 3-phase AC standard voltages

Voltages/frequencies											
Volt [3~]	220	230	380	380	400	400	415	440	460	480	500
Hz	60	50	50	60	50	60	50	60	60	60	50

Table 2: 1-phase AC standard voltages

Voltages/frequencies				
Volt [1~]	110 – 120	110 – 120	220 – 240	220 – 240
Hz	50	60	50	60

Table 3: 3-phase AC special voltages

Voltages/frequencies								
Volt [3~]	220	240	525	575	575	600	660	690
Hz	50	50	50	50	60	60	50	50

Table 4: 1-phase AC special voltages

Voltages/frequencies	
Volt [1~]	208
Hz	60

Further options for version with electronic position transmitter in actuator

Position feedback signal (option)	Analogue output E2 = 0/4 – 20 mA (load max. 500 Ω)
Wiring diagram (basic version)	MSP1110KC3--F18E1 TPA00R1AA-1E1-000

Service conditions	
Use	Indoor and outdoor use permissible
Mounting position	Any position
Installation altitude	≤ 2,000 m above sea level > 2,000 m above sea level on request
Ambient temperature	Standard: –30 °C to +70 °C
	Option: –60 °C to +60 °C, extreme low temperature version
	Low temperature versions incl. heating system for connection to external power supply 230 V AC or 115 V AC
Humidity	Up to 100 % relative humidity across the entire permissible temperature range

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Service conditions		
Enclosure protection in accordance with IEC 60529	IP68	
	Terminal compartment additionally sealed against interior of actuator controls (double sealed)	
	According to AUMA definition, enclosure protection IP68 meets the following requirements: • Depth of water: maximum 8 m head of water • Continuous immersion in water: maximum 96 hours • Up to 10 operations during immersion • Modulating duty is not possible during immersion.	
Pollution degree according to IEC 60664-1	Pollution degree 4 (when closed), pollution degree 2 (internal)	
Vibration resistance according to IEC 60068-2-6	1 g, for 10 to 200 Hz Resistant to vibration during startup or for plant failures. However, a fatigue strength may not be derived from this. (Not valid in combination with gearboxes)	
Corrosion protection	Standard:	KS: Suitable for use in areas with high salinity, almost permanent condensation, and high pollution.
	Options:	KX: Suitable for use in areas with extremely high salinity, permanent condensation, and high pollution. KX-G: Same as KX, however aluminium-free version (outer parts)
Coating	Double layer powder coating	
Colour	Standard:	AUMA silver-grey (similar to RAL 7037)
	Option:	Available colours on request
Accessories		
Wall bracket	For actuator controls mounted separately from the actuator, including plug/socket connector. Connecting cable on request. Recommended for high ambient temperatures, difficult access, or in case of heavy vibration during service. Cable length between actuator and actuator controls is max. 100 m (not suitable for version with potentiometer in the actuator). Instead of the potentiometer, the actuator has to be equipped with an electronic position transmitter.	
Further information		
Weight	Approx. 7 kg (with AUMA plug/socket connector)	
EU Directives	Machinery Directive 2006/42/EC Low Voltage Directive 2014/35/EU EMC Directive 2014/30/EU RoHS Directive 2011/65/EU	